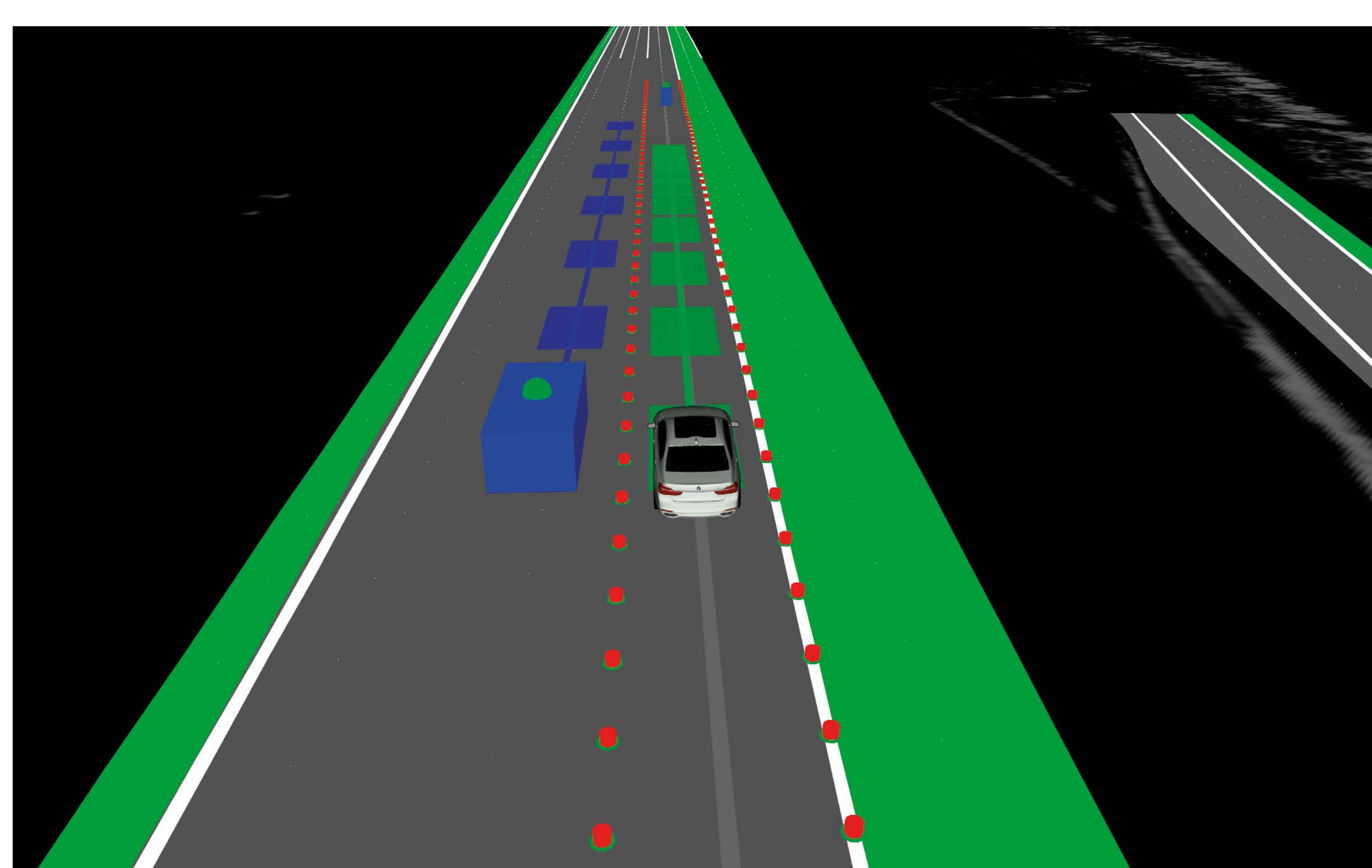


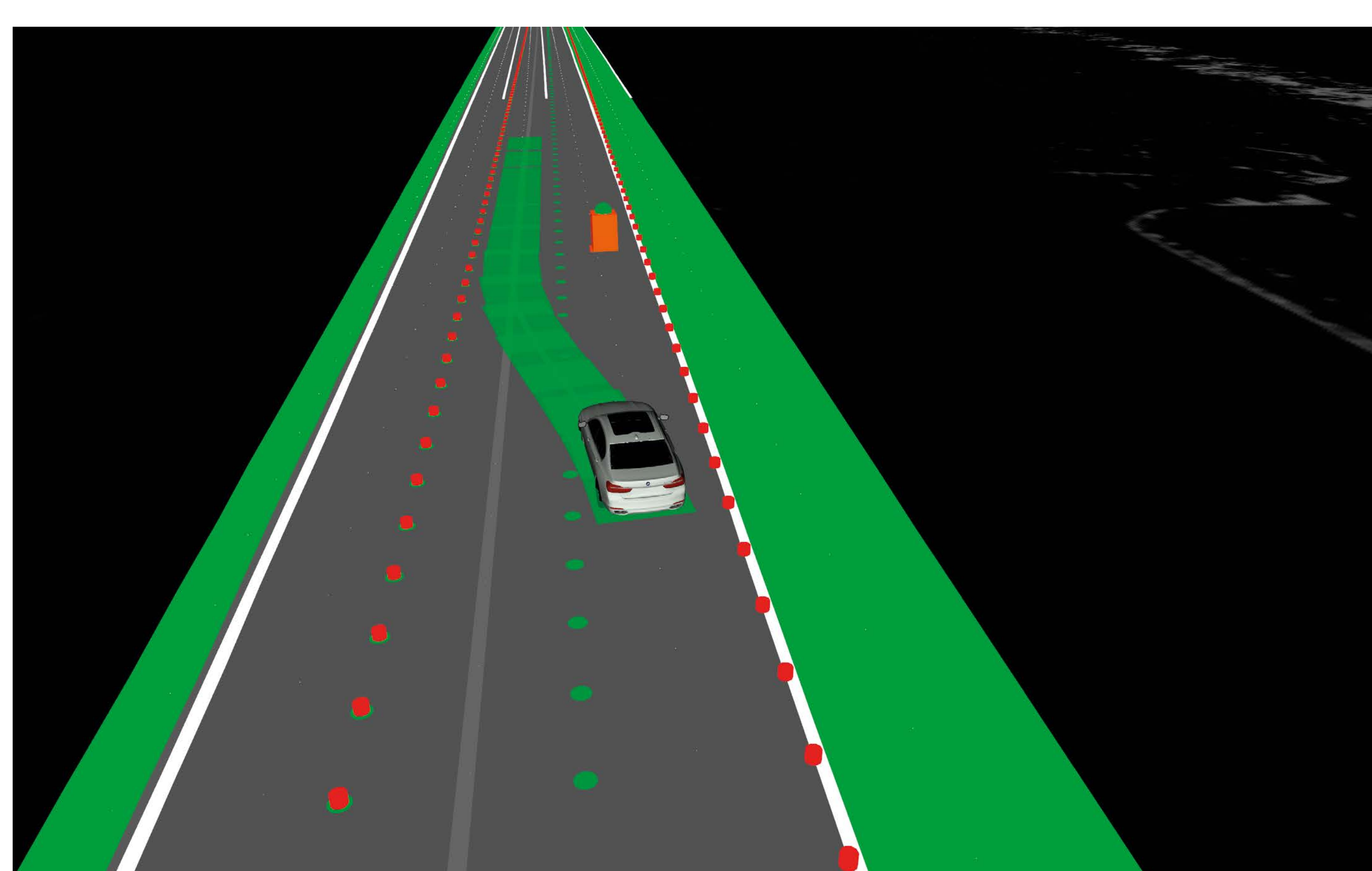


2. Stopping in front of obstacle

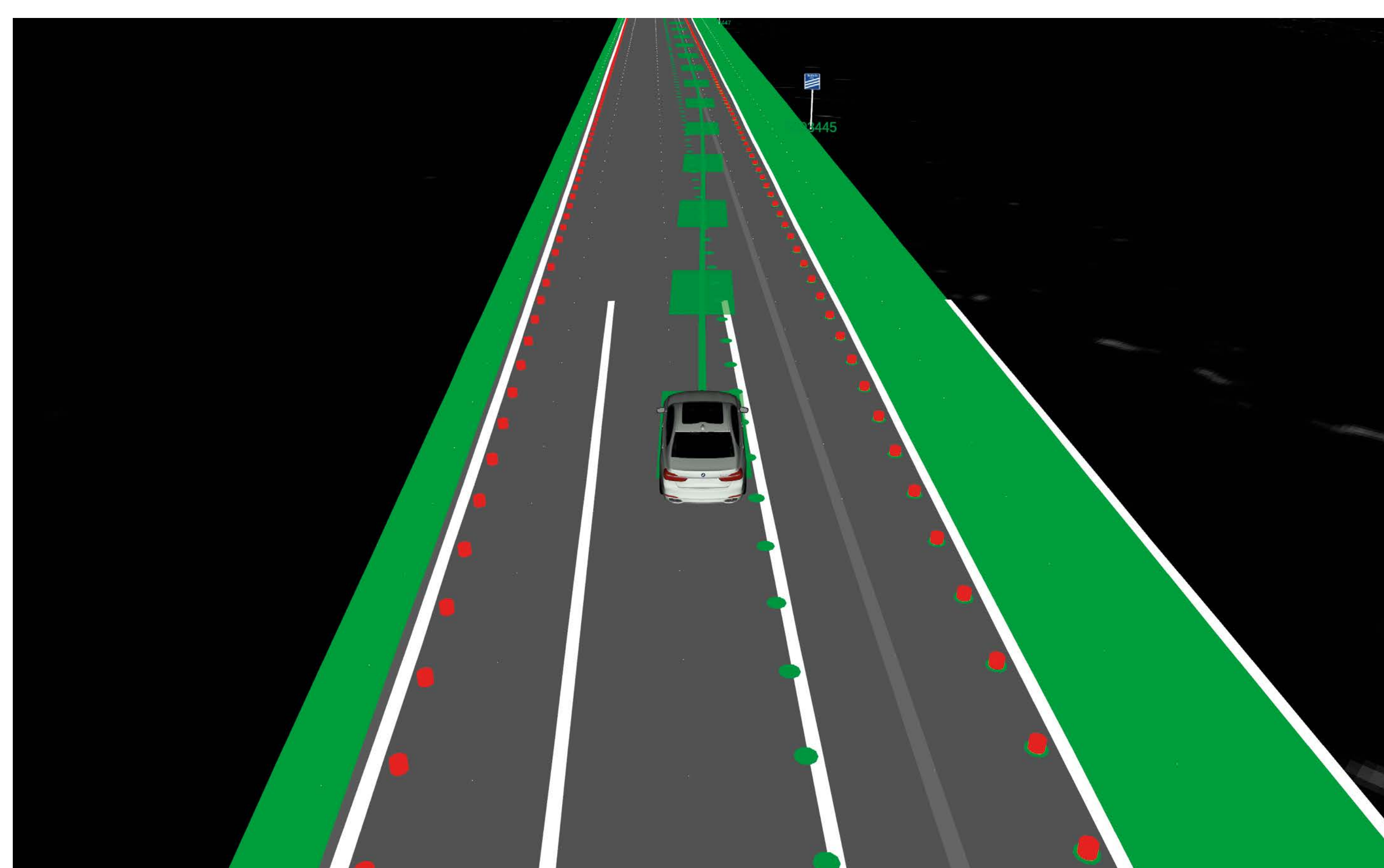
The vehicle receives information about an obstacle on the lane. It will try to perform a lane change. In this scenario, the left lane remains blocked. The vehicle will indicate the lane change wish and decelerate. If the car on the left lane remains uncooperative, the vehicle will stop.



3. When the left lane becomes free, the vehicle will change lanes to avoid the obstacle on the right lane.



4. After passing the obstacle, the vehicle will change back to the rightmost lane, observing the obligation to drive on the righthand side.



5. The vehicle will follow a planned route and exit the highway. It will request a takeover from the driver when exiting.

